

# Optimising maintenance operations in photovoltaic solar plants using data analysis for predictive maintenance

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# Overview

Background

Theoretical background

Analysis

Conclusion & future work

# Motivation



Importance of reliability



Consequence of unexpected failure



Trade off: avoiding unexpected failure vs. exploiting full potential lifetime

# Goals



Conduct a proof of concept for predicting RUL (Remaining Useful Lifetime) using data science

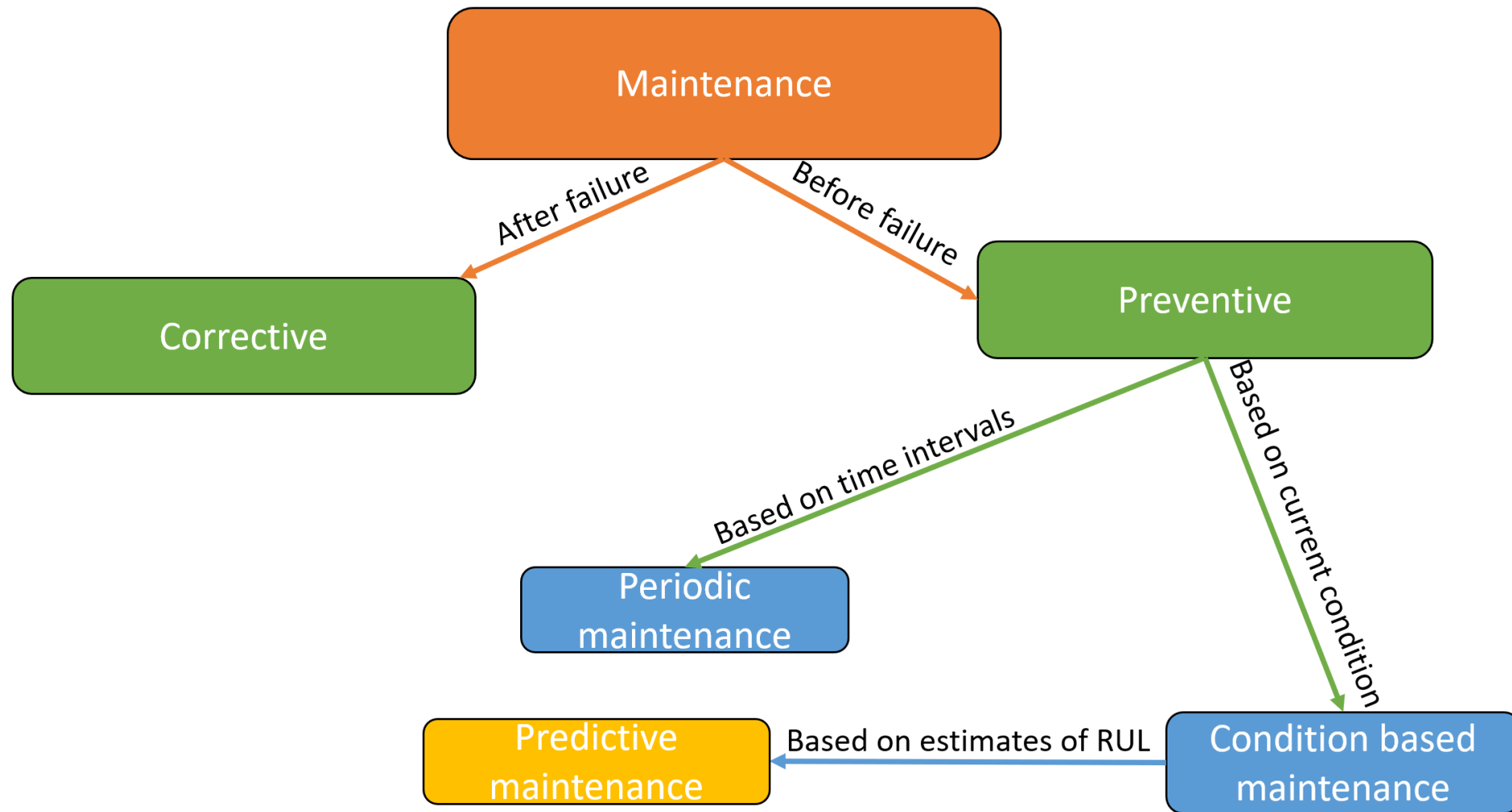


Make use of statistical and machine learning models

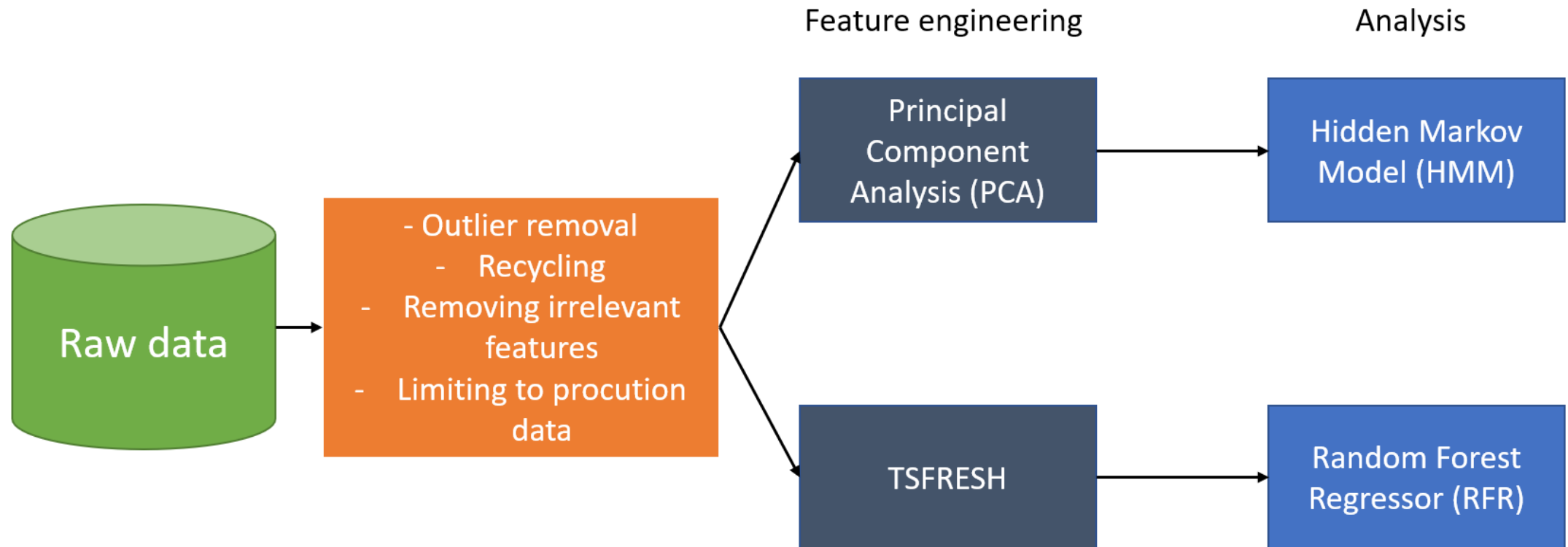


Evaluate and compare the competing approaches

# Predictive maintenance



# Proposed pipelines



# Methodology

# Principal Component Analysis (PCA)

## Working method

- Dimensionality reduction
- Creates new features from input features– principal components

## User choice

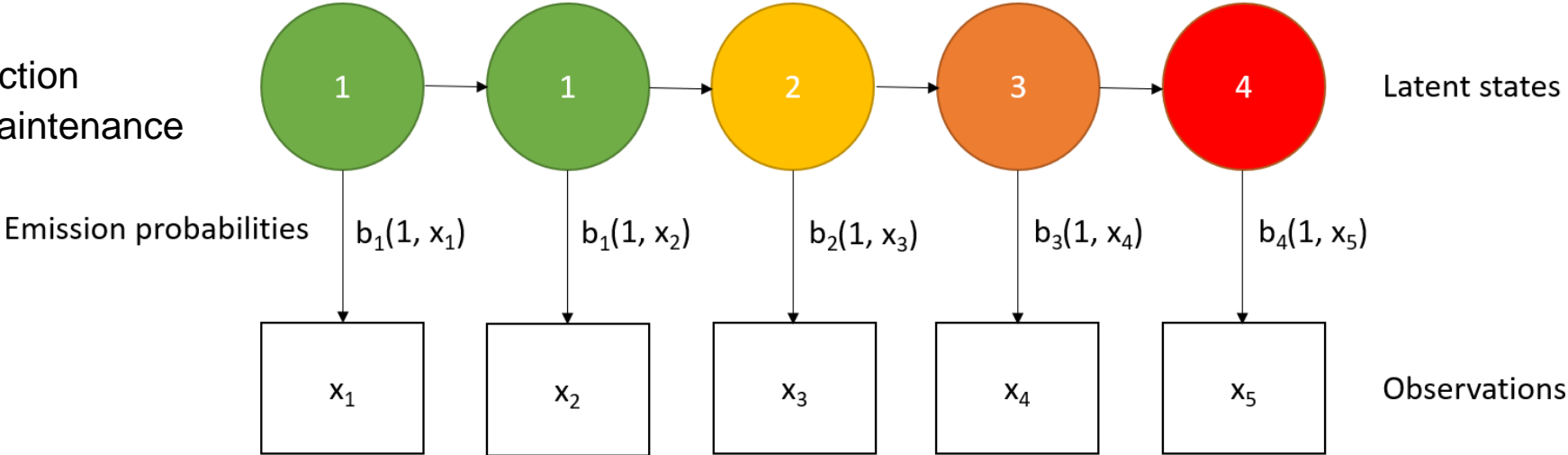
- Trade-off: number of features in output vs. explained variance



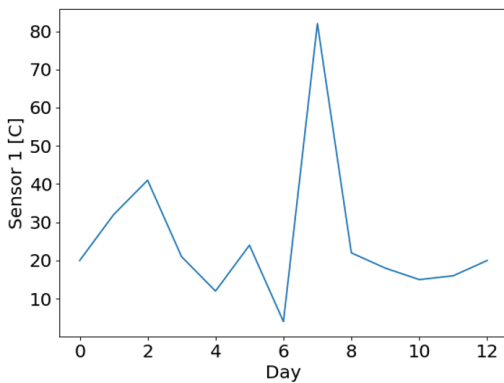


# Hidden Markov Model

- A statistical method, unsupervised, probability based
  - Assumptions
- Parameters
  - Number of states
  - Start probability
  - Transition probability matrix
  - Covariance type
- Endpoint predicted state
  - Possibilities for RUL prediction
  - Use state for predictive maintenance



# TSFRESH – Time Series Feature Extraction using Scalable Hypothesis test<sup>1</sup>



- 16 data points
- 1 Attribute
- 1 Period
- 1 ID



S1.Peaks	S1.Mean	S1.Median	...	S1.max
3	25,15	20.0	...	82

- 1 data point per period per ID
- 789 new attributes per attribute

## Automated feature extraction method

- Temporally invariant and variant information

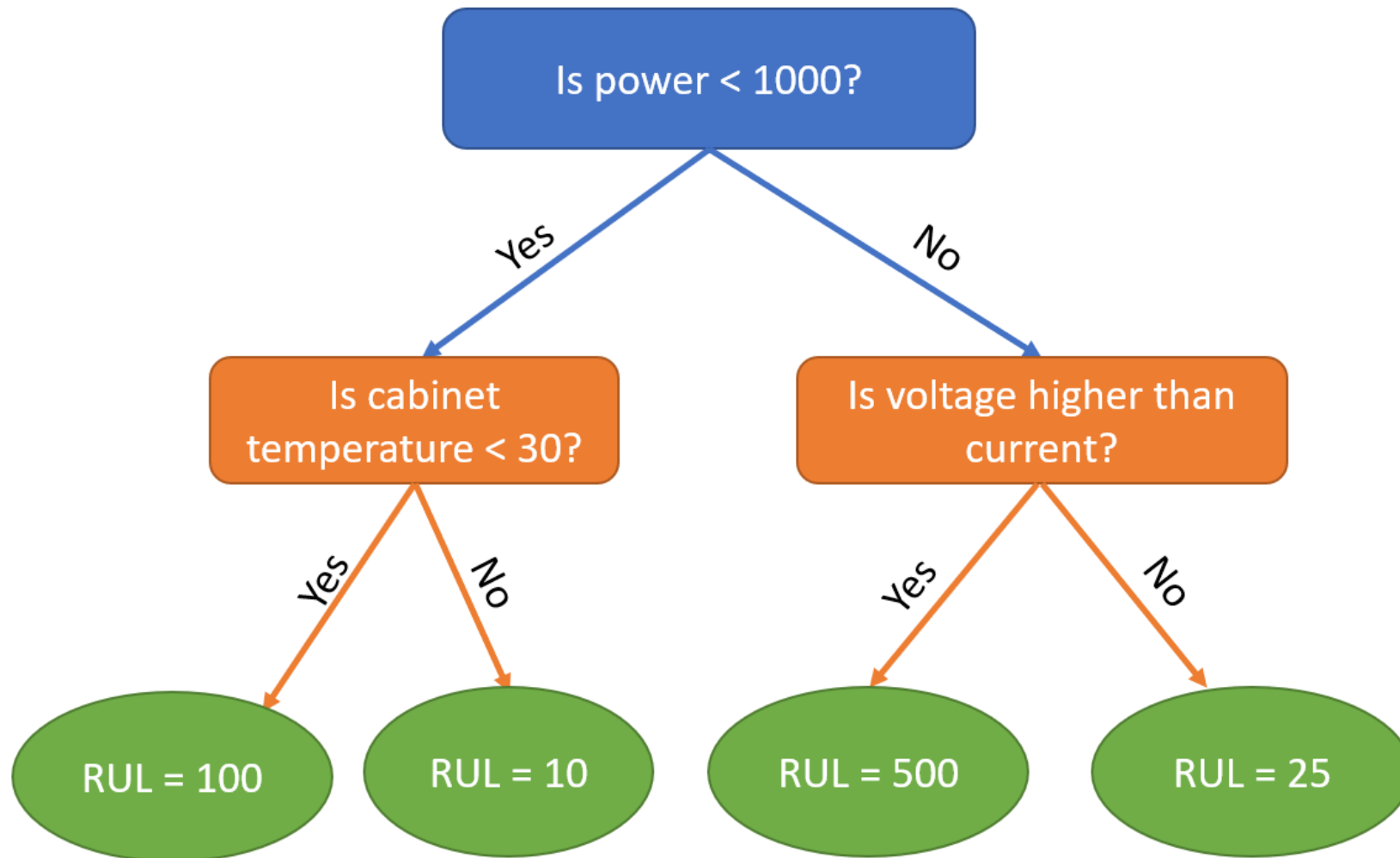
## Summarizing time series into one row

- 789 new columns per feature in the input data
- 77 functions with different parameter settings

## Feature selection

- Scalable Hypothesis test
- Benjmini-Yeuketeli – eliminating false discovery

# Random Forest Regressor



# Experiments

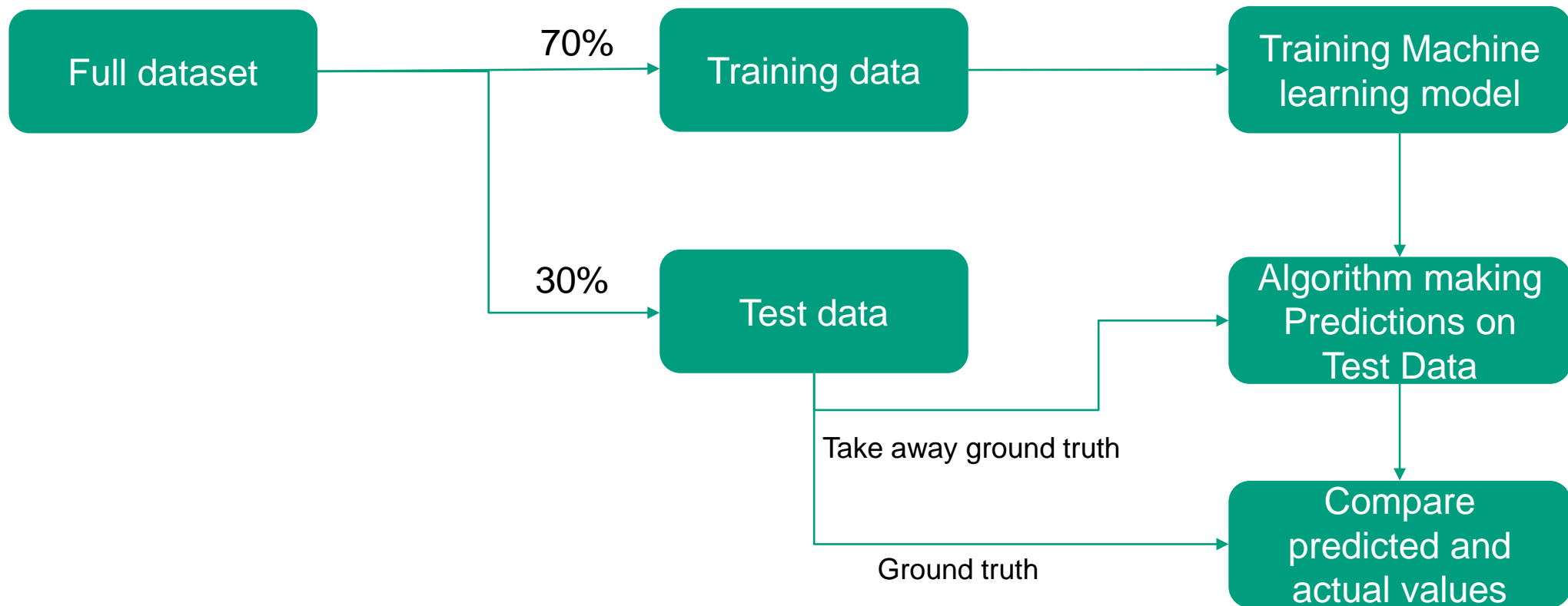


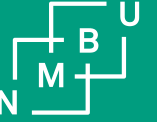
# Data background

- All Inverters and weather stations in all Egypt plants
  - Sampled every minute from June 2019 to 2022
  - Resampled to be every 30 minutes by mean value aggregation
- One certain failure type determined for prediction

Inverter	Timestamp	s1 DC power	s1 DC voltage	s1 DC current	s1 Phase 1 module temperature	...	Status	Irradiation horizontal	Irradiation incline
01	06.05.2019 08:00	855,19	1193,29	718,75	83,5	...	164	998,4	1037,0
01	06.05.2019 08:30	1031,68	1143,38	910,16	93,1	...	164	1025,4	1037,4
01	06.05.2019 09:00	1226,49	1095,22	1123,15	105,3	...	164	1035,9	1039,4

# Experimental setup



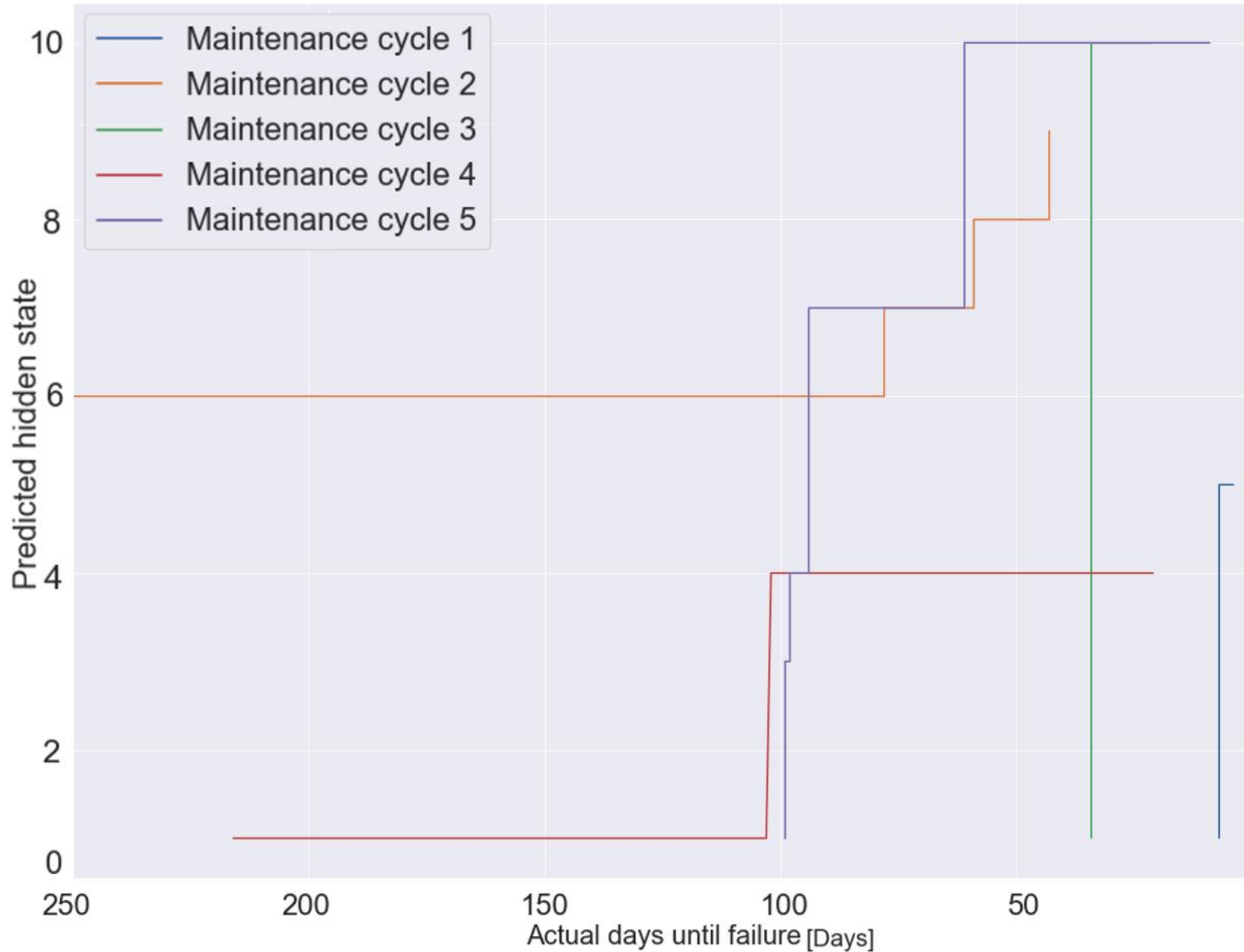


# Approach 1

Degree of failure risk using a statistical Hidden Markov Model

# Results

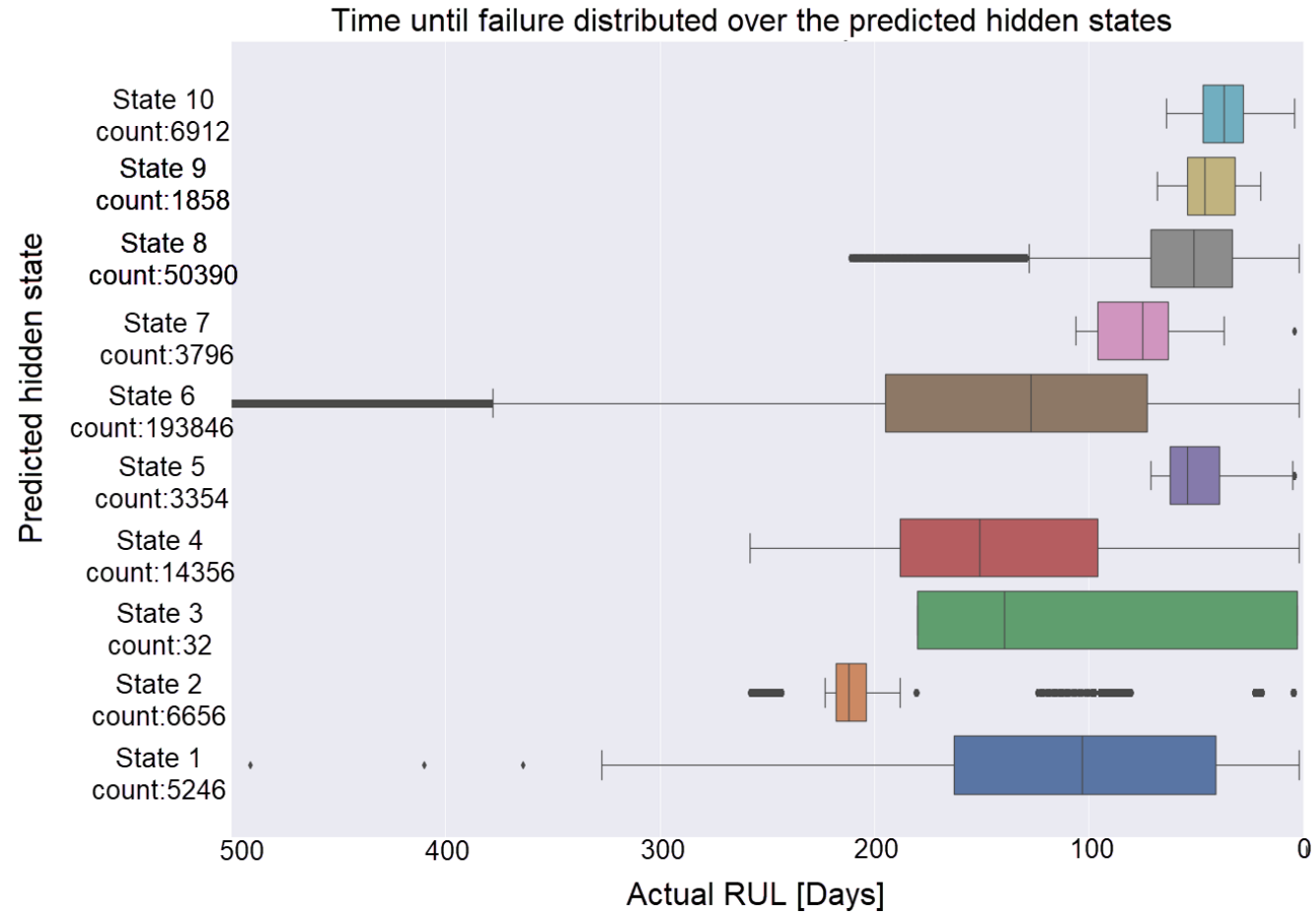
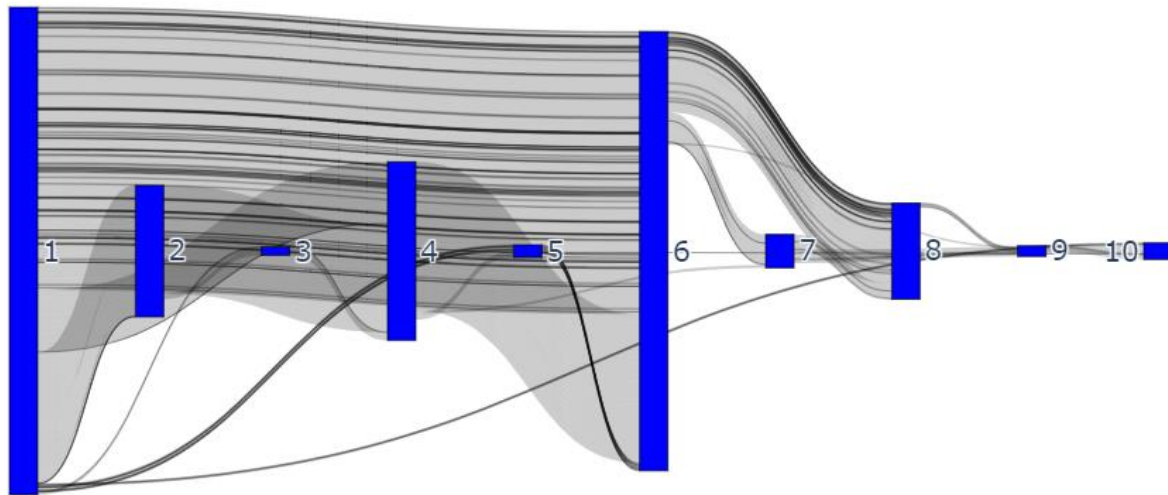
## HMM state prediction for example maintenance cycles

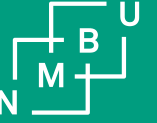




# Results

Sankey plot for state migration



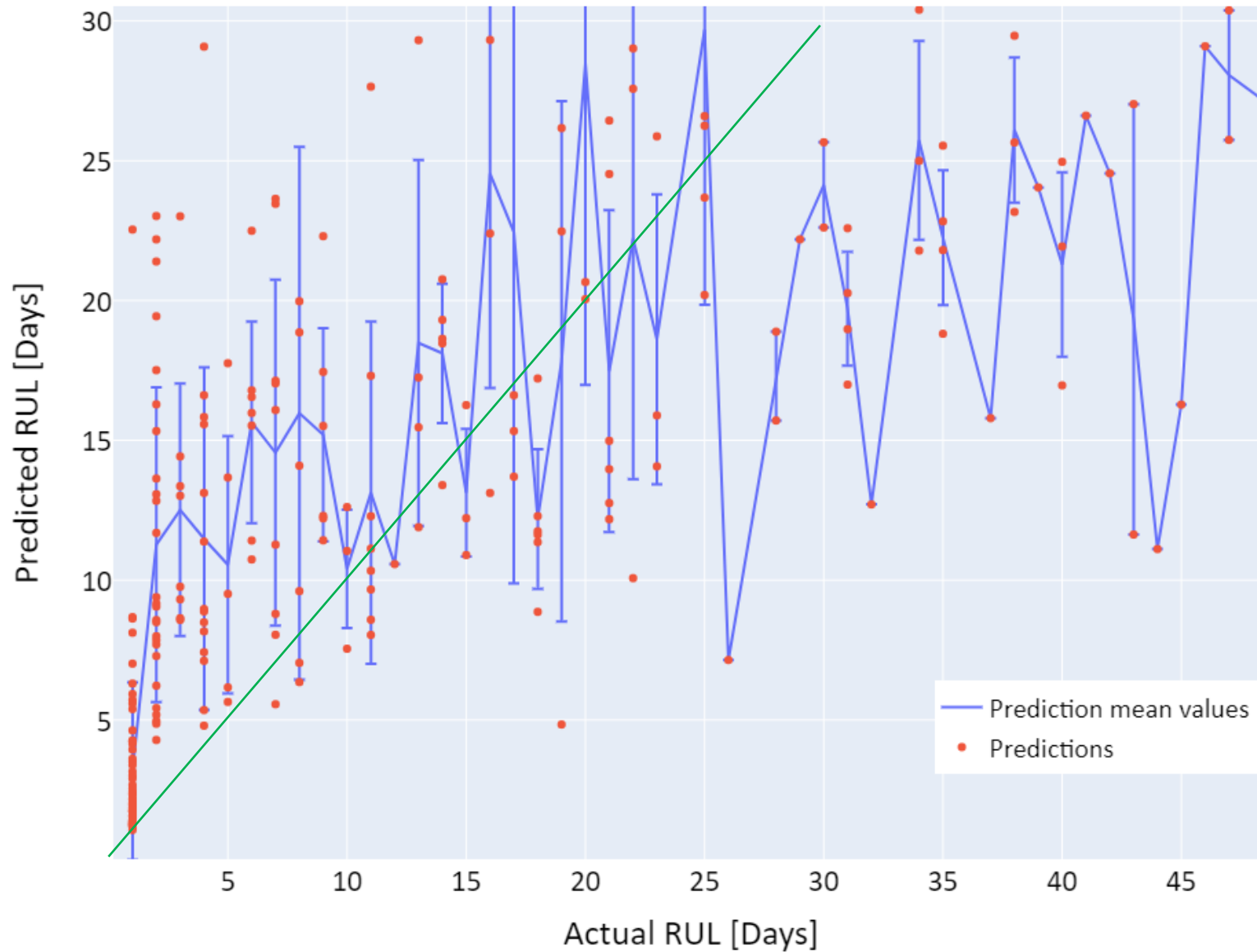


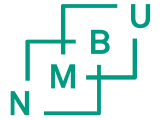
# Approach 2

Machine learning algorithm estimating the time until failure at a given point in time

Predictions of RUL, with error bars showing standard deviation

# Results





# Results

- Feature importances
- Randomness
- Relevance – feedback from experts

Feature name	Importance
Total_Capacitive_Reactive_Energy_in_the_inverter_symmetry_looking_r_0.3	0.37
Section_2_Status_symmetry_looking_r_0.1	0.14
Liquid_Cooling_flow_variance_larger_than_standard_deviation	0.13
Section_2_DC_Power_Measurement_has_duplicate	0.08
Section_1_Phase_3_power_module_temperature_has_duplicate	0.07
Line_Voltage_Measurement_of_Phases_2_and_3_large_standard_deviation_r_0.1	0.07
Section_2_Phase_2_power_module_temperature_large_standard_deviation_r_0.25	0.06

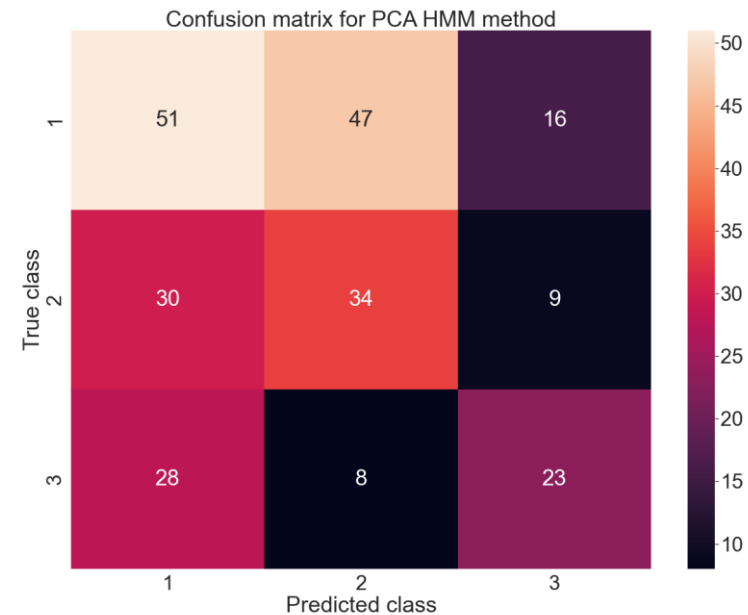
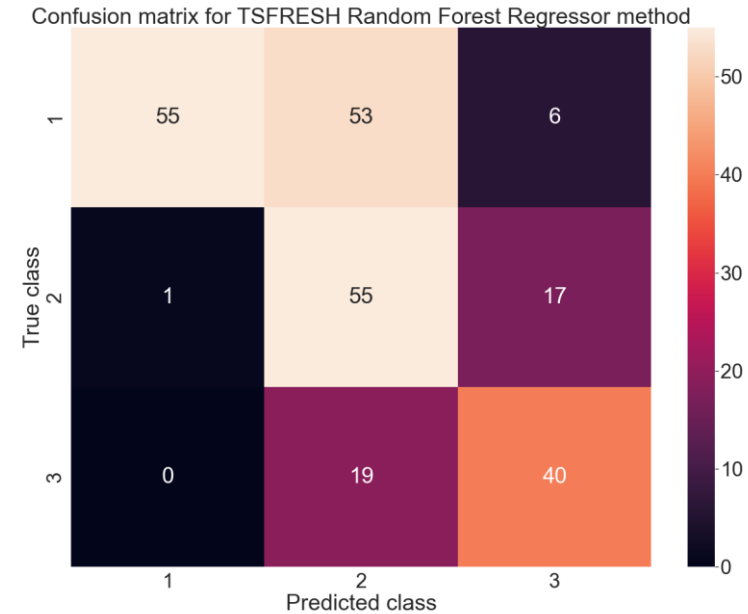
# Comparing the methods

- Common benchmark process
  - Prediction transformed to risk class

Prediction	RFR	HMM
Risk 1	[0, 5]	[8, 10]
Risk 2	(5, 20]	[5, 7]
Risk 3	(20, $\infty$ )	[1, 4]

- Confusion matrices

- Interpretation



# Conclusion and Future Work



## What do these results show?

There is a potential of predictive maintenance using data currently sampled



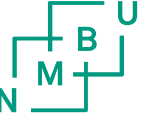
## How can it be improved, what are the next steps?

- Remove errors not leading to downtime
- Testing on various geographical locations
- Implementing an infrastructure for data analysis and displaying results
- Testing upsampling of data with large RUL



## How do the two approaches compare?

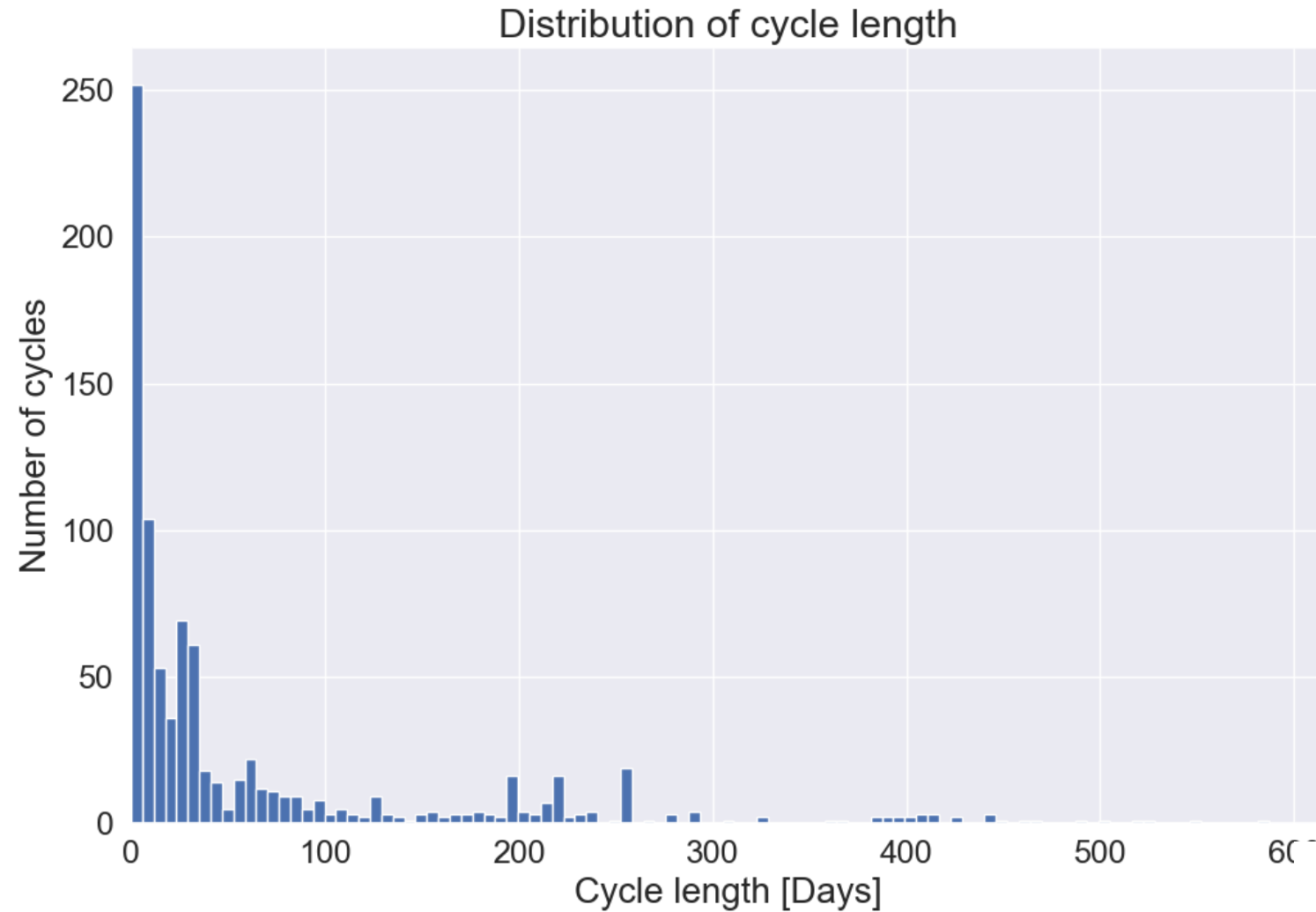
RFR seems to be more stable in the confusion matrix  
Differences in outputs and predictions



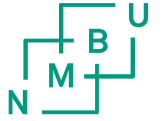
# Thank you for your attention!

- Questions?
- Feel free to contact me or further questions or comments
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  - LinkedIn: [Gøran Sildnes Gedde-Dahl](#)

# Exploratory data analysis







# Preprocessing

## Filtering

- Non-production data
- Data from periods of failure
- Non-physical values
- Removing irrelevant columns (i.e. Error columns)

## Outlier removal

- Extreme values indicating sensor error

## Re-sampling maintenance cycles

- Random ending point before failure, maximum 50 days

# Experimental setup: Re-sampling of maintenance cycles

