Predictive Control Charts (PCC): Bayesian Approach in Online Monitoring of Short Runs

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- PCC will utilize the available prior information (or adopt an objective Bayesian approach in case of prior ignorance) and it will be formed as a sequentially updated region based on the predictive distribution.
- PCC will be introduced in a general form, allowing to handle data of any univariate (discrete or continuous) distribution, as long as this distribution is a member of the k-Parameter Regular Exponential Family (k-PREF).

$$f(\boldsymbol{X}|\boldsymbol{\theta}) = \left[\prod_{j=1}^{n} g(x_j)\right] [c(\boldsymbol{\theta})]^n \exp\left\{\sum_{i=1}^{k} \eta_i(\boldsymbol{\theta}) \sum_{j=1}^{n} h_i(x_j)\right\}$$

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- Our main interest is in detecting in an online fashion and without employing a phase I exercise, the presence of large transient shifts (outliers) on the unknown parameter(s) θ.

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where $\mathbf{Y} = (y_1, \dots, y_{n_0})$ are the historical data, $0 \le \alpha_0 \le 1$ is a scalar parameter, $\pi_0(\boldsymbol{\theta}|\boldsymbol{\tau})$ is the **initial prior** for the unknown parameter(s) and $\boldsymbol{\tau}$ is the vector of the initial prior hyperparameters.

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- From a subjective Bayesian point of view, $\pi_0(\cdot)$ should reflect all available information regarding the unknown parameter(s) **before** the data become available, using prior knowledge, expert's opinion etc.
- From an objective Bayesian point of view we can adopt for $\pi_0(\cdot)$ a weakly informative or even non-informative initial prior, such as flat/Jeffreys/reference/... prior.

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where $\theta \in \Theta$ (parameter space) and $\tau = (\tau_0, \tau_1, \dots, \tau_k)$ is the (k+1)-dimensional vector of the initial prior hyperparameters (reflect the prior knowledge, ranging from highly informative to vague and even non-informative choices).

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- PCC construction will be based on the predictive distribution and it can start as soon as n = 2 and is based on the sequentially updated form of the predictive distribution.
- Precisely, we will determine an IC region, R_{n+1} , where the future observable (X_{n+1}) will most likely be, as long as the process is stable (i.e. no changes occurred).

PCC: Highest Predictive Density/Mass (HPrD/M)

• Assume the set R^c which contains the values of the predictive density (or mass) function, which are greater than a threshold c, i.e.:

 $R^{c} = \{x_{n+1} : f(x_{n+1} | \boldsymbol{X}, \boldsymbol{Y}, \alpha_{0}, \boldsymbol{\tau}) \geq c\}$

The HPrD/M region will be given by minimizing the absolute difference of a highest predictive probability from a significance level $1 - \alpha$, for all the possible values of *c*. Specifically:

$$R_{n+1} = \min_{R^c} \left| \int_{R^c} f(\mathbf{x}_{n+1} | \mathbf{X}, \mathbf{Y}, \alpha_0, \mathbf{\tau}) - (1 - \alpha) \right|,$$

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• R_{n+1} will be the shortest region with the smallest absolute difference from the probability $1 - \alpha$.

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If N is either unknown in advance or it is too large, then we suggest to derive α using the metric of IC Average Run Length (ARL₀):

$$\alpha \approx \frac{1}{ARL_0}$$

PCC: Illustration and Decision Making



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- We generate 100,000 iterations of N = 30 data points from the IC states, which are: N(0,1), P(2) and Bin(20,0.1)
- The OOC states represent isolated shifts of size {2.5 or 3}×sd, which are introduced to the IC sequences at one of the locations: {5, or 15 or 25}.

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- For each setup, we will make use of two initial priors (reference/objective and weakly informative) with the absence or the presence of $n_0 = 10$ historical data \boldsymbol{Y} . Thus, we will have four versions of PCC (with/without prior knowledge, with/without historical data). The initial priors $\pi_0(\cdot|\boldsymbol{\tau})$, which we will employ are:

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 - Normal: reference prior $\pi_0(\theta_1, \theta_2^2) \propto 1/\theta_2^2 \equiv NIG(0, 0, -1/2, 0)$ or the weakly informative NIG(0, 2, 1, 0.8).

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 - Binomial: reference prior $\pi_0(\theta_4) \propto 1/\sqrt{\theta_4(1-\theta_4)} \equiv Beta(1/2, 1/2)$ or the weakly informative Beta(0.5, 4.5).

PCC: Initial Priors (Sensitivity Analysis)



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- The goal is to accurately detect any transient parameter shift of large size, as this will have an impact on the reported patient results. Thus, it is of major importance to perform on-line monitoring of the process without a phase I exercise.
- We elicit the prior $\pi_0(\theta_1, \theta_2^2 | \boldsymbol{\tau}) \sim NIG(29.6, 1/7, 2, 0.56^2)$ and we had $n_0 = 30$ historical data (from a different reagent).



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- In this data set neither prior information regarding the unknown parameter nor historical data exist. Therefore, we use the reference prior as initial prior for θ , i.e. $\pi_0(\theta|\tau) \propto 1/\sqrt{\theta} \equiv G(1/2,0)$ and we also set $\alpha_0 = 0$ for the power prior term.





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We introduced the Predictive Control Chart (PCC) mechanism which attempts to solve the online control/monitoring of phase I or short run data, but can be used in phase II data as well. Specifically, PCC:

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- A library in R has been developed and it is available via Github at https://github.com/BayesianSPCM/BSPCM

- We are grateful to Frederic Sobas from Hospices Civils de Lyon, who provided the data set used in the Normal PCC, but more importantly for his invaluable feedback from using the suggested PCC (along with other Bayesian SPC/M methods) at the daily Internal Quality Control routine in the medical labs of Hospices Civils de Lyon.
- The was partially funded by the Research Center of the Athens University of Economics and Business (RC/AUEB).



Thank you! Questions?